



SRR 308 Short Range Radar Sensor

Safe - reliable - good performance - small design

Continental offers a new type of radar sensor, the **SRR 308-21**, as a possible adaption in different application.

Measuring procedure

The rugged **SRR 308-21** sensor from Continental measures independent the distance and velocity (Doppler's principle) to objects without reflector in one measuring cycle due basis of PCM (Pulse Compression Modulation) with very fast ramps, with a real time scanning of app. 25/sec.. A special feature of the device is the simultaneously measurement of distances up to 95m, relative velocity and the angle relation between two or several objects.

Typical areas of application

- › Simple anti-collision protection for vehicles of every description (particul. autonomous)
- › Headway control for mid distance field (vehicles of every description, particularly autonomous)
- › Area monitoring system for mid field, e.g. of hazardous or non-accessible areas
- › All around recognition for vehicles and different other objects
- › Object detection, e.g. in confusing or unclear areas
- › Unremarkable object detection by affix a protection cover before it

Advantages

- › **Fast and safe:** The **SRR 308-21** dispels with the apparent contradiction between excellent great measuring performance and a high degree of operational safety. The rugged **SRR 308-21** radar sensor is capable of determining the distance to an object in real time scanning and dependent on the driving speed a possible risk of collision.
- › **Reliable:** The **SRR 308-21** radar sensor is fail-safe and able to recognize troubles of the Sensor and sensor environment and display it automatically.
- › **Robust and very small design:** By using a radar technology with less complex measuring principle and the development and mass production in automotive supply industry, the design is kept small in spite of a good performance of the **SRR 308-21**.

SRR 308-21 Short Range Radar 24 GHz - Data Sheet

| Measuring performance | Comment | to natural targets (non-reflector targets) |
|-----------------------------------|---------------------------------|---|
| Distance range | | 0.3 ...95m at 6dBm ₂ (80m at 3dBm ₂) <2 m no accurate distance measuring |
| Resolution distance measuring | | 1.0 m for point targets; target discrimination = 2 x resolution |
| Accuracy distance measuring | for single target | ±0.2 m at distance >2 m / ±0.5 m at distance <2 m |
| Azimuth angle augmentation | (field of view FoV) | -75°...+75° (measurement) -75°...+75° up to -90°...+90° (detection) |
| Elevation angle augmentation | (field of view FoV) | 12° at -6 dB / 16° at -10 dB / 23° at -20 dB |
| Resolution angle measuring | selectivity / separation effect | 14° (14° at 0° azimuth) - targets only with different angle - amplitude difference max 6 dB, otherwise smaller targets will be suppressed |
| Accuracy angle measuring | for single target | -2°...+2° at ±30°(FoV), -4°...+4° at ±60°, -5°...+5° at ±75° |
| Speed measurement range | | -300 km/h...+300 km/h (- leaving objects.+ approximation) |
| Speed measurement resolution | | 1.2 km/h for point targets; target discrimination = 2 x resol. |
| Speed measurement accuracy | | ±0.2 km/h for single targets |
| Target separation (point targets) | possible if it meets | speed difference >2.4 km/h / distance difference > 2.0 m |
| Update rate / transmission cycle | | 40 ms |
| Planar antenna beams - process | receiver / transmitter | 4 Rx / 2 Tx column - digital beam forming with 8 beams |
| Operating conditions | Comment | to natural targets (non-reflector targets) |
| Radar operating frequency band | | 24.05...24.25 GHz (ISM band) |
| Transmission capacity (EIRP) | emitted radar power | app. 18.5 mW = <12.7 dBm average / <20 dBm peak |
| Mains power supply | typ. 12 V DC | +9.0 V...16 V DC full operation, >+16 V DC sensor functions deactivated >+32 V DC overvoltage protection activated (hardware) |
| Power consumption | at 12.0 V DC at 13.8 V DC | app. 3.9 W / 325 mA normal operation - 7.5 A inrush current app. 3.9 W / 280 mA normal operation - 8.5 A inrush current |
| Over voltage protection bus pins | | -40 V...+40 V DC |
| Operating-/ storage temperature | | -40°C...+85°C / -40°C...+95°C |
| Shock | mechanical | 50 g - no mechanical driven components inside |
| Vibration | mechanical | 27,78 m/s ² RMS acceleration at 5 - 2000Hz |
| Protection rating | | IP 6K9K (high-pressure cleaning), dust, ice-water shock test, salt fog resistant, mixed gas EN 60068-2-60 |

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| Displays and connections | Comment | to natural targets (non-reflector targets) |
|--|---------------------------|---|
| Monitoring function | | self monitoring (fail-safe designed) |
| Displays | | none |
| Interface | | 1 x CAN high-speed 500 kbit/s |
| Housing | Comment | to natural targets (non-reflector targets) |
| Dimensions / weight | L * W * H (mm) / mass (g) | 127.2 * 129.6 * 26.5 (80 * 89.3 * 25 without mount / connector) / app. 172g |
| Material | housing / cover | PBT 30GF black colored (Ultradur) / AlMg3 W19 |
| Miscellaneous | | |
| <p>Measuring principle (Doppler's principle) in one measuring cycle due basis of FMCW with very fast ramps independent measurement of distance and velocity</p> <p>Version SRR 308-21 / sensor for the industry / CAN protocol for free communication</p> <p>The version -21 allows to set maximum 8 ID's and maximum 8 collision avoidance regions and to change the sensitivity between low and high sensitivity by the user continuously</p> <p>Interfaces: The device is fitted with two CAN bus interfaces as standard. Further interfaces as converter, software adaption, housing and / or hardware adaption are possible on demand and in case of assumption of costs. The SRR 308-21 also could be used for complex measuring tasks.</p> | | |

